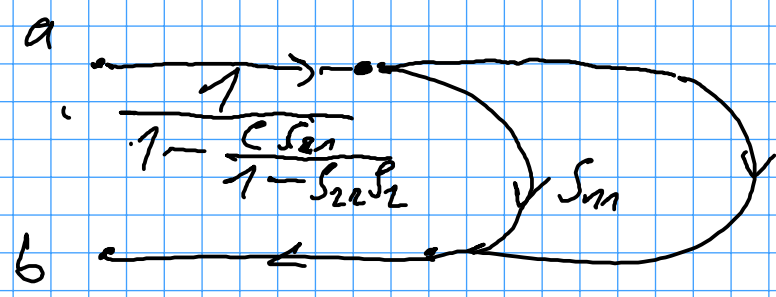
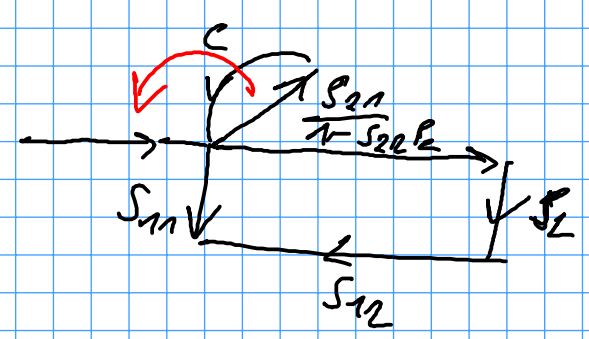
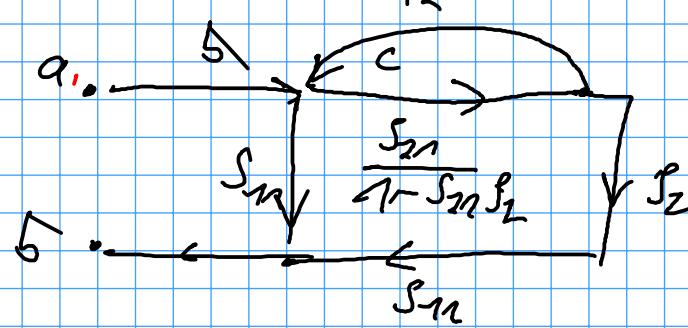
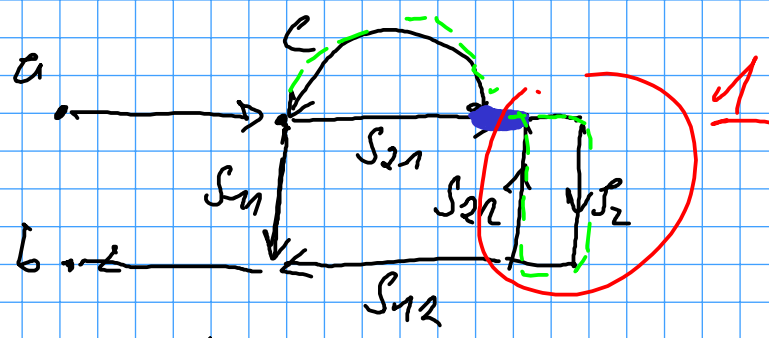


$$\frac{S_{21} P_z S_{12}}{1 - S_{22} P_z}$$

$$\frac{b}{a} = S_{11} + \frac{S_{21} P_z S_{12}}{1 - S_{22} P_z}$$



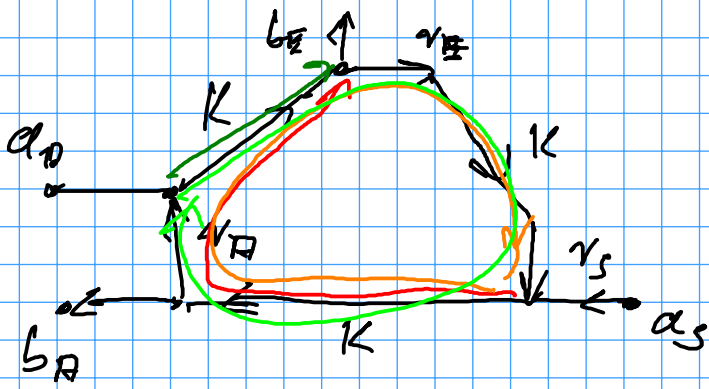
$$\frac{S_{21} P_z S_{12}}{1 - S_{22} P_z}$$

$$\frac{b}{a} = \frac{1}{1 - S_{22} P_z - c S_{21}} \left(S_{11} + \frac{S_{21} P_z S_{12}}{1 - S_{22} P_z} \right)$$

Für Kompensation $S_{22} P_z + c S_{21} = 0$

$$\Leftrightarrow c = - \frac{S_{22} P_z}{S_{21}}$$

passiv realsteher, weil $|c| < 1$ sehr wahrscheinlich



Für a_S

$$a_S \xrightarrow{K \cdot r_A + K} b_E$$

$$\text{Feedback: } b_E \xrightarrow{K \cdot r_A \cdot K \cdot r_B \cdot K \cdot r_S} a_S$$

Für a_A

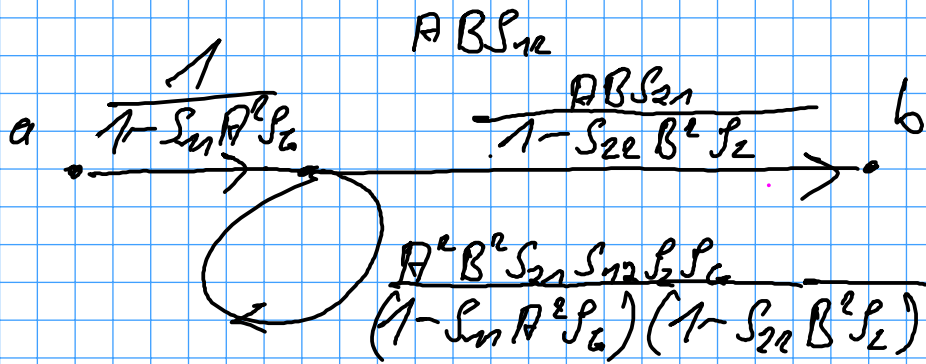
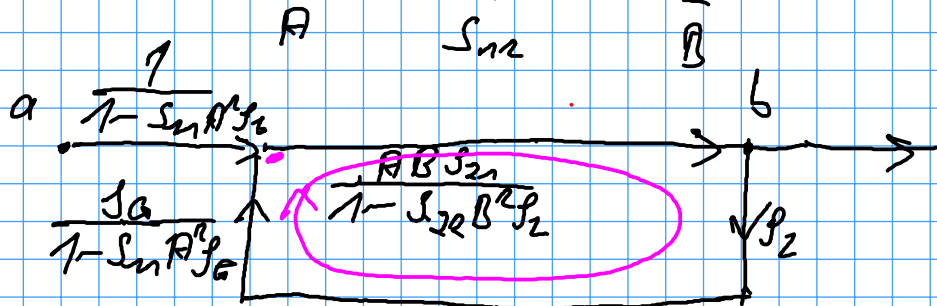
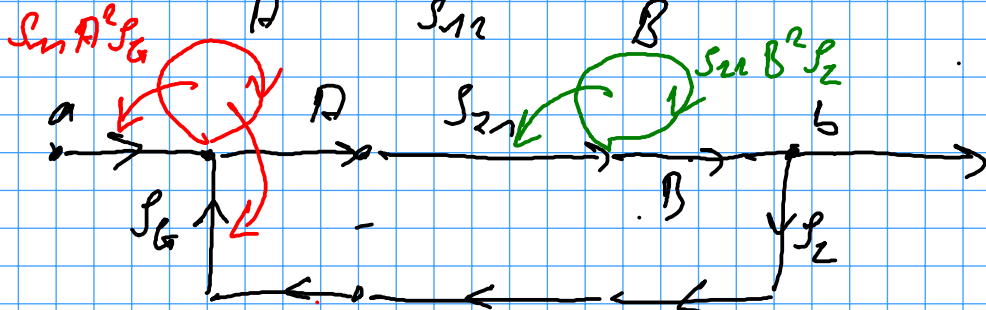
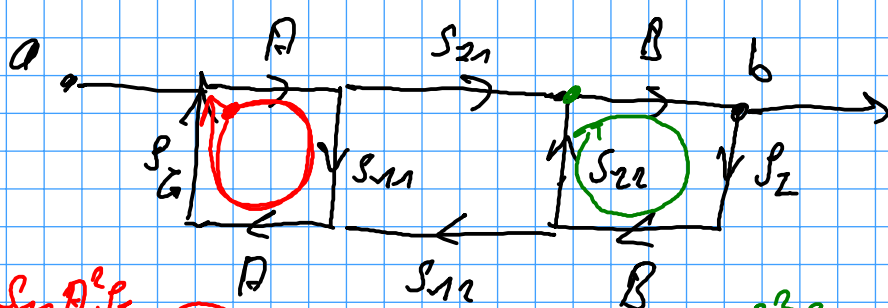
$$a_A \xrightarrow{K} b_E$$

wie oben

$$b_E = \frac{a_S K^2 r_A}{1 - K^3 r_A r_B r_S} + \frac{a_A - K}{1 - K^3 r_A r_B r_S}$$

zu optimieren ist r_A , damit Sender & Empfänger möglichst gut entkoppelt sind.

Der Unterschied zwischen den Pfaden $a_A \rightarrow b_E$ und $a_S \rightarrow b_E$ ist eben $K \cdot r_A$, K soll aber möglichst $|K| \rightarrow 1$ sein, also wenig Verlust im Filterfaktor.



$$\frac{b}{a} = \frac{AB S_{21}}{(1 - S_{11} A^2 P_1)(1 - S_{22} B^2 P_2)}$$

$$= \frac{AB S_{21}}{(1 - S_{11} A^2 P_1)(1 - S_{22} B^2 P_2) - A^2 B^2 S_{21} S_{12} P_1 P_2}$$

$$= \frac{AB S_{21}}{1 - S_{11} A^2 P_1 - S_{22} B^2 P_2 + S_{11} S_{22} A^2 B^2 P_1 P_2 - A^2 B^2 S_{21} S_{12} P_1 P_2}$$

$$J_2 = 0 \quad \frac{b}{a} = \frac{AB S_{21}}{1 - S_{11} A^2 J_G}$$

$$S_{21} = \frac{b}{a} \cdot \frac{1 - S_{11} A^2 J_G}{AB}$$

$$|S_{11}| \rightarrow \pm 1 \quad A = B = 1$$

$$|J_G| = 0,316 ; 0,1$$

$$S_{21} = \frac{b}{a} \cdot (1 \pm 1 \cdot J_G)$$

$$|J_G| = 0,316 \Rightarrow 0,684 \frac{b}{a} \leq S_{21} \leq 1,316 \frac{b}{a}$$

$$|J_G| = 0,01 \Rightarrow 0,9 \frac{b}{a} \leq S_{21} \leq 1,1 \frac{b}{a}$$